# **Bandit Structured Prediction for Neural Seq2Seq Learning**

Julia Kreutzer, Artem Sokolov, Stefan Riezler

Heidelberg University, Germany

#### **Bandit Structured Prediction**

**Algorithm 1** Bandit Structured Prediction Input: Sequence of learning rates  $\gamma_k$ Output: Optimal parameters  $\hat{\theta}$ Initialize parameters  $\theta_0$ for k = 0, ..., K do

Observe input structure  $\mathbf{x}_k$ Sample output structure  $\tilde{\mathbf{y}}_k \sim p_{\theta}(\mathbf{y}|\mathbf{x}_k)$ Obtain feedback  $\Delta(\tilde{\mathbf{y}}_k)$ Compute stochastic gradient  $s_k$ Update parameters  $\theta_{k+1} = \theta_k - \gamma_k s_k$ Choose a solution  $\hat{\theta}$  from the list  $\{\theta_0, \dots, \theta_K\}$ 

## Bandit Seq2Seq

Bandit structured prediction [1] is a stochastic optimization framework where learning is performed from **partial feedback**. This feedback is received in the form of task loss evaluation of a predicted output structure, without having access to gold standard structures.

In this work, we advance the framework by

#### Results

BLEU on held-out in- and out-of-domain test sets for parameters  $\hat{\theta}$  selected by **early stopping** on a validation set.

We seek models for **conservative domain adaptation**, that learn to improve on in-domain, but maintain quality on out-of-domain translations.

# **Objectives**

## **Expected Loss (EL)**:

Expectation of a task loss  $\Delta(\mathbf{\tilde{y}})$  over all input and output structures:

 $L^{\mathsf{EL}}(\theta) = \mathbb{E}_{p(\mathbf{x}) p_{\theta}(\tilde{\mathbf{y}}|\mathbf{x})} [\Delta(\tilde{\mathbf{y}})].$ 

Stochastic gradient:

$$s_k^{\mathsf{EL}} = \Delta(\mathbf{\tilde{y}}) \frac{\partial \log p_{\theta}(\mathbf{\tilde{y}}|\mathbf{x}_k)}{\partial \theta}$$

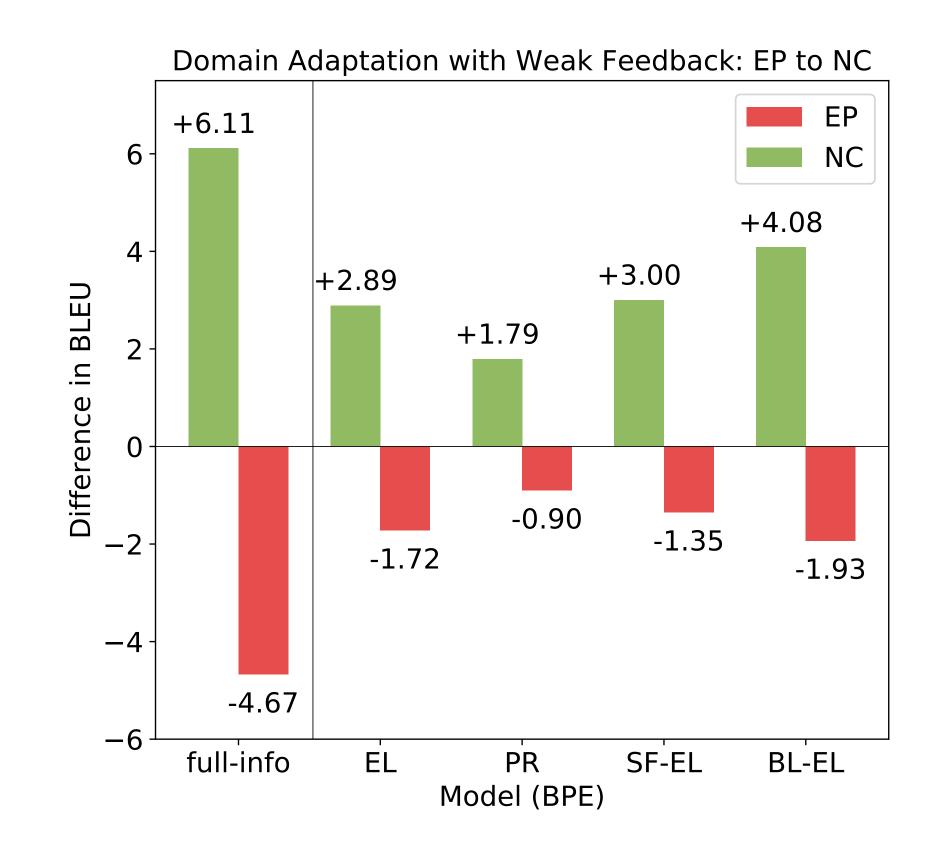
Output structures  $\tilde{\mathbf{y}}$  are sampled word by word from the distribution resulting from the softmax transformation in the output layer of

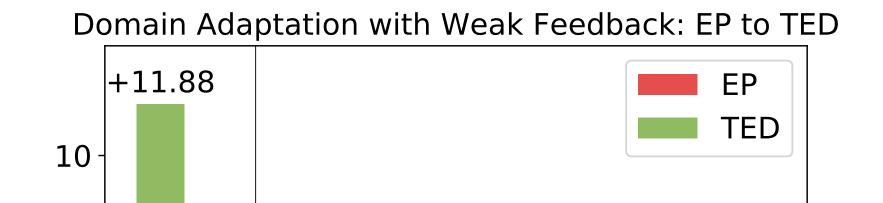
lifting linear bandits to neural seq2seq
 learning using attention-based RNNs, and
 incorporating control variates for variance reduction and improved generalization.

Experiments for **neural machine translation** show large improvements for domain adaptation from simulated bandit feedback.

# **Control Variates**

Augment a random variable X (here:  $X = s_k$ ) by another random variable Y, the control variate. With  $\overline{Y} = \mathbb{E}[Y]$ ,  $X - \hat{c}Y + \hat{c}\overline{Y}$  is an unbiased estimator of  $\mathbb{E}[X]$ . Control variates with high Cov(X, Y) reduce the variance of the gradient estimate. Two choices here:





the network.

**Pairwise Preference Ranking (PR)**:

Transfer EL to **pairs of structures**  $\langle \tilde{\mathbf{y}}_i, \tilde{\mathbf{y}}_j \rangle$ :  $L^{\mathsf{PR}}(\theta) = \mathbb{E}_{p(\mathbf{x}) p_{\theta}(\langle \tilde{\mathbf{y}}_i, \tilde{\mathbf{y}}_j \rangle | \mathbf{x})} [\Delta(\langle \tilde{\mathbf{y}}_i, \tilde{\mathbf{y}}_j \rangle)].$ 

Stochastic gradient:

$$s_{k}^{\mathsf{PR}} = \Delta(\langle \tilde{\mathbf{y}}_{i}, \tilde{\mathbf{y}}_{j} \rangle) \\ \times \left( \frac{\partial \log p_{\theta}(\tilde{\mathbf{y}}_{i} | \mathbf{x}_{k})}{\partial \theta} + \frac{\partial \log p_{\theta}^{-}(\tilde{\mathbf{y}}_{j} | \mathbf{x}_{k})}{\partial \theta} \right).$$

Learn to rank  $\tilde{\mathbf{y}}_i$  over  $\tilde{\mathbf{y}}_j$  with **pairwise** feedback, either continuous (cont)  $\Delta(\langle \mathbf{y}_i, \mathbf{y}_j \rangle) = \Delta(\mathbf{y}_j) - \Delta(\mathbf{y}_i),$ or binary (bin)

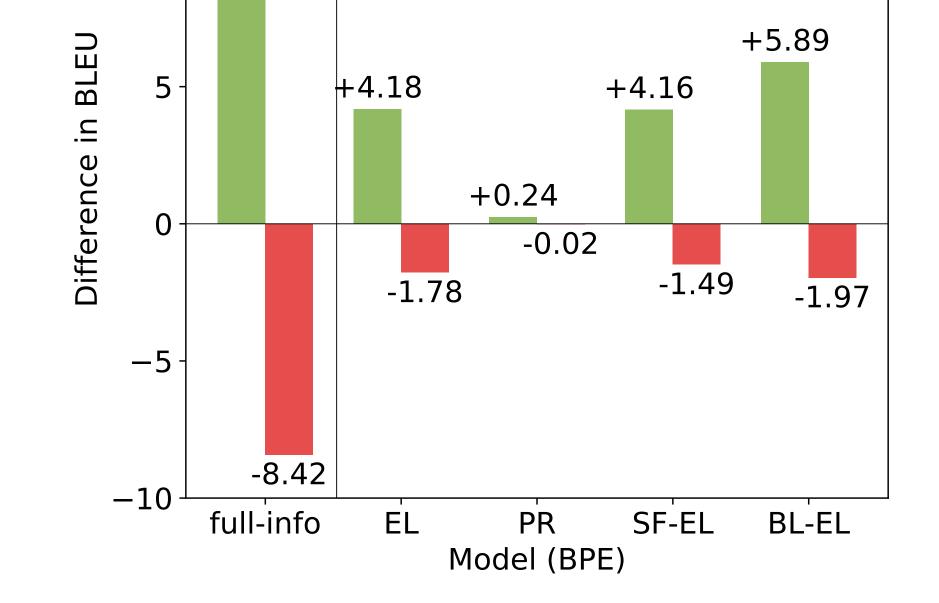
 $\Delta(\langle \mathbf{y}_i, \mathbf{y}_j \rangle) = \begin{cases} 1 & \text{if } \Delta(\mathbf{y}_j) > \Delta(\mathbf{y}_i), \\ 0 & \text{otherwise.} \end{cases}$ 

1 Baseline (BL) [2]:  $Y_{k} = \nabla \log p_{\theta}(\tilde{\mathbf{y}} | \mathbf{x}_{k}) \frac{1}{k} \sum_{j=1}^{k} \Delta(\tilde{\mathbf{y}}_{j}).$ 2 Score Function (SF) [3]:  $Y_{k} = \nabla \log p_{\theta}(\tilde{\mathbf{y}} | \mathbf{x}_{k}).$ 

## **Experiments**

Neural machine translation **domain adaptation**:

- Adapt a pre-trained model (Europarl, fr-en) to new domains (News Commentary and TED).
- Simulated feedback with GLEU on references
- Encoder-decoder architecture with attention
- Full-information baselines: maximum likelihood estimation on reference translations

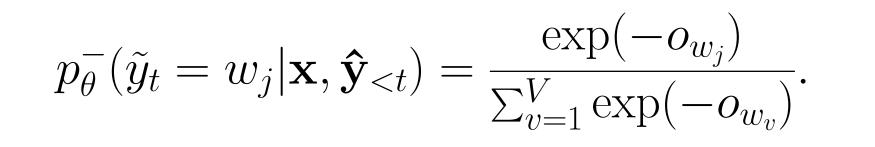


## **Findings**

Successful training of NMT with weak feedback

- Large improvements for domain adaptation, outperforming linear models
- ► Control variates improve generalization, see [6]

Draw **negative sample**  $\tilde{\mathbf{y}}_j$  from distribution  $p_{\theta}^-$ , one word per output structure (chosen randomly):



Strategies for handling of unknown words:
attention-based replacement of UNKs for word-based models [4]
sub-word models with Byte-Pair-Encoding (BPE) [5]

#### Acknowledgements

This research was supported in part by the German research foundation (DFG), and in part by a research cooperation grant with the Amazon Development Center Germany.





## References

[1] A. Sokolov, J. Kreutzer, C. Lo, and S. Riezler. Stochastic structured prediction under bandit feedback. In *NIPS*, Barcelona, Spain, 2016.
 [2] R. J. Williams. Simple statistical gradient-following algorithms for connectionist reinforcement learning. *Machine Learning*, 20:229–256, 1992.
 [3] R. Ranganath, S. Gerrish, and D. M. Blei. Black box variational inference. In *AISTATS*, Reykjavik, Iceland, 2014.
 [4] S. Jean, O. Firat, K. Cho, R. Memisevic, and Y. Bengio. Montreal neural machine translation systems for WMT'15. In *WMT*, Lisbon, Portugal, 2015.
 [5] R. Sennrich, B. Haddow, and A. Birch. Neural machine translation of rare words with subword units. In *ACL*, Berlin, Germany, 2016.
 [6] Moritz Hardt, Ben Recht, and Yoram Singer. Train faster, generalize better: Stability of stochastic gradient descent. In *ICML*, New York, NY, 2016.